

| | 1. Gear | 2. Gear | 3. Gear | 4. Gear | 5. Gear | 6. Gear | R Gear | φ_{ges} |
|------------------|------------------|------------------|---------|---------|---------|---------|--------|-----------------|
| i | 4,84 | 2,98 | 1,90 | 1,41 | 1,0 | 0,77 | -3,28 | 6,32 |
| φ | 1,62 | 1,57 | 1,35 | 1,41 | 1,30 | | | |
| $i_{01} = -3,28$ | $i_{02} = -2,43$ | $i_{01} = -2,43$ | | | | | | |

Fig. 9

| | 1. Gear | 2. Gear | 3. Gear | 4. Gear | 5. Gear | 6. Gear | R Gear | φ_{ges} |
|------------------|------------------|------------------|---------|---------|---------|---------|--------|-----------------|
| i | 3,87 | 2,48 | 1,74 | 1,38 | 1,0 | 0,76 | -3,26 | 5,06 |
| φ | 1,56 | 1,43 | 1,27 | 1,38 | 1,31 | | | |
| $i_{01} = -3,26$ | $i_{02} = -2,87$ | $i_{01} = -1,71$ | | | | | | |

Fig. 10

| | 1. Gear | 2. Gear | 3. Gear | 4. Gear | 5. Gear | 6. Gear | R Gear | φ_{ges} |
|------------------|------------------|------------------|---------|---------|---------|---------|--------|-----------------|
| i | 3,83 | 2,30 | 1,62 | 1,30 | 1,0 | 0,79 | -3,67 | 4,88 |
| φ | 1,67 | 1,42 | 1,25 | 1,30 | 1,27 | | | |
| $i_{01} = -3,67$ | $i_{02} = -2,83$ | $i_{01} = -2,22$ | | | | | | |

Fig. 11

| GEAR | K1 | K2 | B1 | B2 | B3 |
|-----------------------|----------|----------|----------|----------|----------|
| 1 | | | | \times | \times |
| 2 | | | \times | | \times |
| 3 | \times | | | | \times |
| 4 | | \times | | | \times |
| 5 | \times | \times | | | |
| 6 | | \times | \times | | |
| R | \times | | | \times | |
| gebremstes Neutral | | | \times | \times | |

Fig. 12

Braked